(3) If $S \in \mathrm{~F}$ and $x \in G$, then $S^{x} \in \mathrm{~F}$.

For a Fitting set F of $G$, the F -injector of $G$ is similarly defined as the F-injector for Fitting class $F$ (see [1, Definition VIII. (2.5)]).

Hartley [4] proved that for any soluble Fitting class F (that is, all groups in F are soluble), every F-injector $V$ of a soluble group $G$ either covers or avoids every chief factor $H / K$ of $G$, that is, either $(V \cap H) K=H$ or $(V \cap H) K=K$.

In this connection, the problem arises in the class of non-soluble groups, describe the cover-avoid property of F -injectors of a group $G$ on its chief factors.

For any set F of subgroups of $G$, we let $\sigma(\mathrm{F})=\cup_{\mathrm{G} \in \mathrm{F}} \sigma(G)$.
It is proved
Theorem. Let F be a Fitting set of a group $G$ and $\varnothing \neq \pi \subseteq \mathbb{P}$. Then every F-injector of $G$ either covers or avoids every chief factor of $G$ in each of the following cases:

1) $G \subseteq \mathrm{~F} \circ \mathrm{~S}^{\pi}$, where $\pi=\sigma(\mathrm{F})$;
2) $G \subseteq \mathrm{~S}^{\pi}$ and $\mathrm{F} \circ \mathrm{E}_{\pi^{\prime}}=\mathrm{F}$.

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## ON THE POSITIVE INTEGER SOLUTION

OF NONLINEAR EQUATIONS $X^{2}+A X=B$ AND $X^{3}+X^{2}+B X=C$ FOR THE SECOND ORDER MATRICES

K. Yakuto<br>VSU named after P.M. Masherov, Vitebsk, Belarus

The problem of finding integer positive solution of nonlinear matrix equations of polynomial type for matrices of various orders plays an important role in solving a wide range of problems associated with the modeling of economic, social processes [1, c. 189].

The aim of this work is to find the simplest method for solving matrix equations for the second order matrices.

Material and methods. The matrix equation was recorded in the form of a system consisting of four equations, which were solved by analytical
methods. In the process of the study, a package of symbolic mathematics Maple 18 was used.

Results and their discussion. Consider the nonlinear matrix equation

$$
\begin{equation*}
X^{2}+A X=B \tag{1}
\end{equation*}
$$

where $X=\left(\begin{array}{ll}a & b \\ c & d\end{array}\right), A=\left(\begin{array}{ll}\alpha & \beta \\ \gamma & \delta\end{array}\right), B=\left(\begin{array}{cc}K & L \\ M & N\end{array}\right)$.
Lemma 1. To find a matrix-root of equation (1), it is necessary for each possible value of the variable $a$ to solve the quadratic equation $f b^{2}+(a+\alpha+g+\beta f) b-L+\beta g=0$, for the variable $b$, where $f=\frac{m}{k}, g=\frac{m \beta-k a-k \delta}{k}, k=K-a^{2}-\alpha a, m=M-\gamma a ;$ the variables $c$ and $d$ can be found using the connection formula for these variables with variable $d: c=\frac{k}{\beta+b}, d=f b+g$. The estimate for the variable $a$ has the form: $1 \leq a \leq \sqrt{K-1-\alpha-\beta}$.

Proof. In this case, the system of equations corresponding to equation (1) will have the following form:

$$
\left\{\begin{array}{l}
a^{2}+b c+\alpha a+\beta c=K,  \tag{2}\\
b(a+d)+\alpha b+\beta d=L, \\
c(a+d)+\gamma a+\delta c=M \\
b c+d^{2}+\gamma b+\delta d=N .
\end{array}\right.
$$

We consider the first and third equations of system (2). Introducing the new variables $k$ and $m: k=K-a^{2}-\alpha a, m=M-\gamma a$, we obtain a system of equations (3):

$$
\left\{\begin{array}{l}
b c+\beta c=k,  \tag{3}\\
c(a+d)+\delta c=m .
\end{array}\right.
$$

Solving the system (3), we can find a formula expressing the relationship between the variables $b$ and $d: d=f b+g$, where $f=\frac{m}{k}, g=\frac{m \beta-k a-k \delta}{k}$. Substituting it into the second equation of system (2), we obtain an equation of the second order with respect to the variable $b$ :

$$
\begin{equation*}
f b^{2}+(a+\alpha+g+\beta f) b-L+\beta g=0 \tag{4}
\end{equation*}
$$

Solving equation (4) with respect to the variable $b$, we can find the variable $d$, and the variable $c$ can be found using the first equation of system (3).

To find an asymmetric matrix-root of equation (1) under the condition that the matrices A and B are not symmetric matrices, it is necessary for each
possible value of the variable $a$ to solve the quadratic equation for the variable $b$ and using the coupling formulas to find the values of the variables $c$ and $d$.

Consider the nonlinear matrix equation

$$
\begin{equation*}
X^{3}+A X^{2}+B X=C \tag{5}
\end{equation*}
$$

where $X=\left(\begin{array}{ll}a & b \\ c & d\end{array}\right), A=\left(\begin{array}{ll}\alpha & \beta \\ \gamma & \delta\end{array}\right), B=\left(\begin{array}{cc}\varepsilon & \varphi \\ \psi & \mu\end{array}\right), C=\left(\begin{array}{ll}K & L \\ M & N\end{array}\right)$.
Lemma 2. To find a matrix-root of equation (5), it is necessary for the variable $b$ to solve the quadratic equation $p s b^{2}+(k r-n p+s q) b-n q=0$, where $p=2 a+d+\alpha, \quad r=a+2 d+\delta, \quad q=\beta(a+d)+\varphi, \quad s=\gamma(a+d)+\psi$, $k=K-a^{3}-\alpha a^{2}-\varepsilon a, \quad n=N-d^{3}-\delta d^{2}-\mu d$. The variable $c$ can be found using the relation formula with the variable $b: c=\frac{k}{b p+q}$. The estimate for the variable a has the form: $1 \leq a \leq \sqrt[3]{K-3-2 \alpha-\varepsilon-2 \beta-\varphi}$. The estimate for the variable $d$ has the form: $1 \leq d \leq \sqrt[3]{N-3-2 \gamma-\psi-2 \delta-\mu}$.

Proof. In this case, the system of equations corresponding to equation (5) will have the following form:

$$
\left\{\begin{array}{l}
a^{3}+2 a b c+b c d+\alpha a^{2}+\alpha b c+\beta a c+\beta c d+\varepsilon a+\varphi c=K,  \tag{6}\\
a^{2} b+b^{2} c+a b d+b d^{2}+\alpha a b+\alpha b d+\beta b c+\beta d^{2}+\varepsilon b+\varphi d=L, \\
a^{2} c+b c^{2}+a c d+c d^{2}+\gamma a^{2}+\gamma b c+\delta a c+\delta c d+\psi a+\mu c=M, \\
a b c+2 b c d+d^{3}+\gamma a b+\gamma b d+\delta b c+\delta d^{2}+\psi b+\mu d=N .
\end{array}\right.
$$

Consider the first and fourth equations of system (6):

$$
\left\{\begin{array}{l}
b c p+c q=k, \\
b c r+b s=n . \tag{7}
\end{array}\right.
$$

where $k=K-a^{3}-\alpha a^{2}-\varepsilon a, n=N-d^{3}-\delta d^{2}-\mu d, p=2 a+d+\alpha$, $q=\beta(a+d)+\varphi, r=a+2 d+\delta, s=\gamma(a+d)+\psi$.

Expressing the variable $c$ from the first equation of system (7), we obtain:

$$
\begin{equation*}
c=\frac{k}{b p+q} \tag{8}
\end{equation*}
$$

Substituting expression (8) into the second equation of system (7), we obtain an equation of the second order with respect to the variable $b$ :

$$
\begin{equation*}
p s b^{2}+(k r-n p+s q) b-n q=0 \tag{9}
\end{equation*}
$$

To solve the problem it is necessary to solve the quadratic equation (9) for each possible pair of values of the variables $a$ and $d$ to find the variable $b$, using the formula (8), to find the value of the variable $c$.

To solve the matrix equation (5), we can use the following program written in Pascal.

Var W, X, Y, Z, a, d, m1, t1, alpha, beta, gamma, delta, epsilon, fi, psi, $\mathrm{mu}, \mathrm{k}, \mathrm{n}$ : integer; b1, b2, c1, c2, m, t, p, q, r, s, dis, u1, u2, v1, v2: real;
begin
$\operatorname{read}(\mathrm{W}, \mathrm{X}, \mathrm{Y}, \mathrm{Z}$, alpha, beta, gamma, delta, epsilon, fi, psi, mu);
$\mathrm{m}:=$ power(W-3-2*alpha-epsilon-2*beta-fi, 1/3); $\mathrm{m} 1:=\operatorname{trunc}(\mathrm{m})$;
$\mathrm{t}:=$ power(Z-3-2*gamma-psi-mu-2*delta, 1/3); t1:=trunc(t);
for $\mathrm{a}:=1$ to ml do begin $\mathrm{k}:=\mathrm{W}-\mathrm{a} * \mathrm{a}^{*} \mathrm{a}$-alpha*a*a-epsilon*a;
for $\mathrm{d}:=1$ to t 1 do begin $\mathrm{n}:=\mathrm{Z}-\mathrm{d} * \mathrm{~d}^{*} \mathrm{~d}-\mathrm{delta}^{*} \mathrm{~d}^{*} \mathrm{~d}-\mathrm{mu}{ }^{*} \mathrm{~d}$;
$\mathrm{p}:=2^{*} \mathrm{a}+\mathrm{d}+$ alpha; $\quad \mathrm{q}=$ =beta* $(\mathrm{a}+\mathrm{d})+\mathrm{fi} ; \quad \mathrm{r}:=\mathrm{a}+2^{*} \mathrm{~d}+$ delta;
$\mathrm{s}:=\mathrm{gamma}^{*}(\mathrm{a}+\mathrm{d})+\mathrm{psi}$;
dis: $=\left(\mathrm{k} * \mathrm{r}-\mathrm{n} * \mathrm{p}+\mathrm{s}^{*} \mathrm{q}\right) *(\mathrm{k} * \mathrm{r}-\mathrm{n} * \mathrm{p}+\mathrm{s} * \mathrm{q})+4 * \mathrm{p} * \mathrm{~s}^{*} \mathrm{n}^{*} \mathrm{q} ;$
if dis>0 then begin
b1:=(-k*r+n*p-s*q+sqrt(dis))/(2*p*s); c1:=k/(b1*p+q);
$\mathrm{b} 2:=(-\mathrm{k} * \mathrm{r}+\mathrm{n} * \mathrm{p}-\mathrm{s} * \mathrm{q}-\mathrm{sqrt}(\mathrm{dis})) /(2 * \mathrm{p} * \mathrm{~s}) ; \mathrm{c} 2:=\mathrm{k} /(\mathrm{b} 2 * \mathrm{p}+\mathrm{q})$;
$\mathrm{u} 1:=\mathrm{frac}(\mathrm{b} 1) ; \mathrm{u} 2:=\mathrm{frac}(\mathrm{c} 1) ; \mathrm{v} 1:=\mathrm{frac}(\mathrm{b} 2) ; \mathrm{v} 2:=\mathrm{frac}(\mathrm{c} 2)$; end;
if $(\mathrm{b} 1>0)$ and $(\mathrm{c} 1>0)$ and $(\mathrm{u} 1=0)$ and $(\mathrm{u} 2=0)$ then begin
writeln(a); writeln(b1); writeln(c1); writeln(d); writeln('Next') end;
if ( $\mathrm{b} 2>0$ ) and $(\mathrm{c} 2>0)$ and $(\mathrm{v} 1=0)$ and ( $\mathrm{v} 2=0$ ) then begin
writeln(a); writeln(b2); writeln(c2); writeln(d); writeln('Next'); end;
end; $\mathrm{d}:=\mathrm{d}+1$; end; $\mathrm{a}:=\mathrm{a}+1$; end.
Conclusion. It was shown that we can use analytical methods for solving the problem of finding positive integer solution of matrix equations of polynomial type for second-order matrices.

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